

TABLE 1. Line and Surface Integrals

Integral	of a function $f$	of a vector field $\vec{F}$
over a curve $C$	$\int_C f ds = \int_a^b f(\vec{r}(t)) \vec{r}'(t)  dt$	$\int_C \vec{F} \cdot d\vec{r} = \pm \int_a^b \vec{F}(\vec{r}(t)) \cdot \vec{r}'(t) dt$
over a surface $S$	$\iint_S f dS = \iint_D f(\vec{r}) \vec{r}_u \times \vec{r}_v  dA$	$\iint_S \vec{F} \cdot d\vec{S} = \pm \iint_D \vec{F}(\vec{r}) \cdot (\vec{r}_u \times \vec{r}_v) dA$

- $\int_C \vec{F} \cdot d\vec{r}$  can also be written as  $\int_C Pdx + Qdy(+Rdz)$ , where  $P$ ,  $Q$  (and  $R$ ) are the components of  $\vec{F}$ .
- The integral of a vector field over a curve has the “−” sign if the direction in which  $t$  increases does not match the orientation of the curve  $C$ .
- The integral of a vector field over a surface has the “−” sign if the normal vector  $\vec{r}_u \times \vec{r}_v$  does not match the orientation of the surface  $S$ .
- Alternative ways of finding  $\int_C \vec{F} \cdot d\vec{r}$ :
  - if  $\vec{F}$  is conservative, can use FTC: find a function  $f$  such that  $\nabla f = \vec{F}$ , and take the difference of its values at the endpoints of  $C$ .
  - in two dimensions: if  $C$  is a simple closed curve, can use Green’s theorem

$$\int_C Pdx + Qdy = \iint_D (Q_x - P_y)dA$$

if  $C$  has counterclockwise (positive) orientation; otherwise insert −.

- In the surface integrals,  $D$  is the parameter domain for  $u$  and  $v$ .
- If  $\vec{r}(x, y) = \langle x, y, g(x, y) \rangle$ , then  $\vec{r}_x \times \vec{r}_y = \langle -g_x, -g_y, 1 \rangle$
- Stokes’ theorem relates two types of integrals of vector fields:

$$\int_C \vec{F} \cdot d\vec{r} = \iint_S \text{curl } \vec{F} \cdot d\vec{S}$$

where  $C$  is a simple closed curve that bounds the surface  $S$ , and both are oriented according to the right-hand rule.

- The divergence theorem is an easy way to integrate a vector field over a closed surface:

$$\iint_S \vec{F} \cdot d\vec{S} = \iiint_E \text{div } \vec{F} dV$$

where  $S$  has positive (outward) orientation, and  $E$  is the solid bounded by  $S$ .